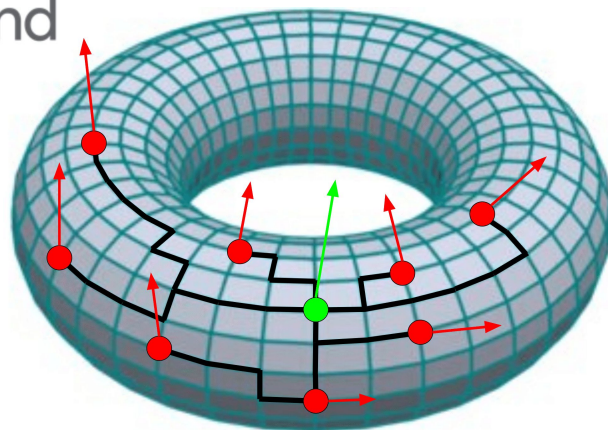


Efficient Graph Field Integrators Meet Point Clouds

Krzysztof Choromanski, Arijit Sehanobish*, Han Lin*, Yunfan Zhao*, Eli Berger, Tetiana Parshakova, Alvin Pan, David Watkins, Tianyi Zhang, Valerii Likhoshesterov, Somnath Basu Roy Chowdhury, Kumar Avinava Dubey, Deepali Jain, Tamas Sarlos, Snigdha Chaturvedi, Adrian Weller*



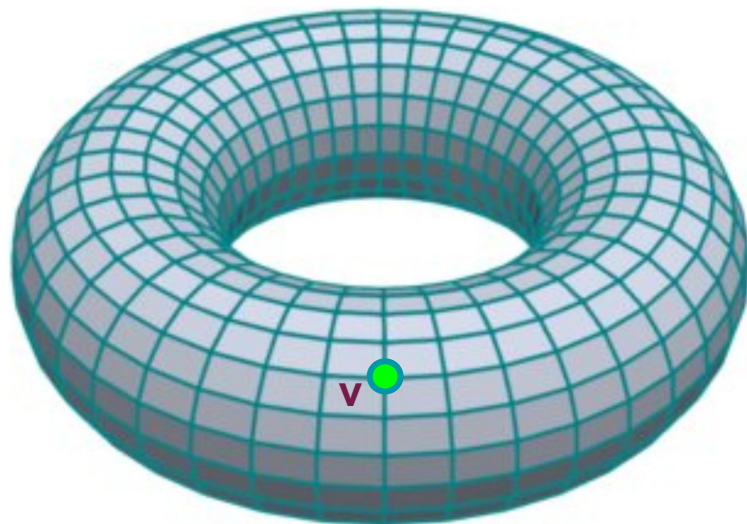
* equal contribution



Problem formulation: Efficient Graph Field Integration

Compute efficiently (in the sub-quadratic time in the number of nodes \mathbf{N} of the graph) the following expressions **for every node v** of the given graph G

$$i(v) := \sum_{w \in V} K(w, v) \mathcal{F}(w)$$

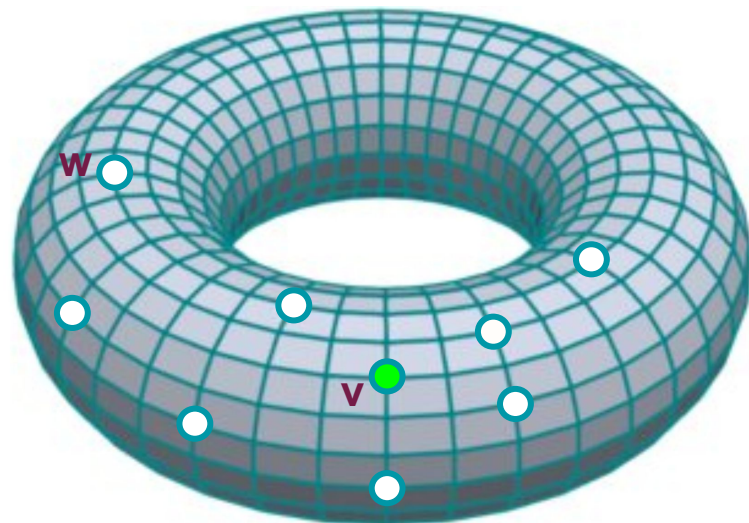


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over all the
nodes



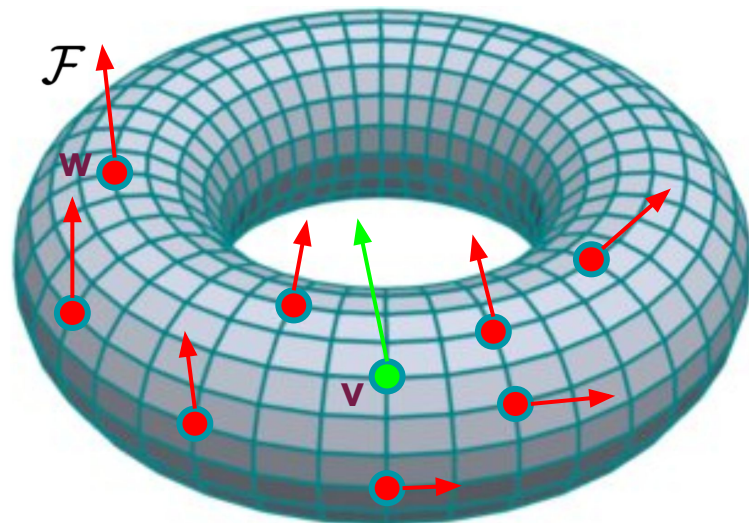
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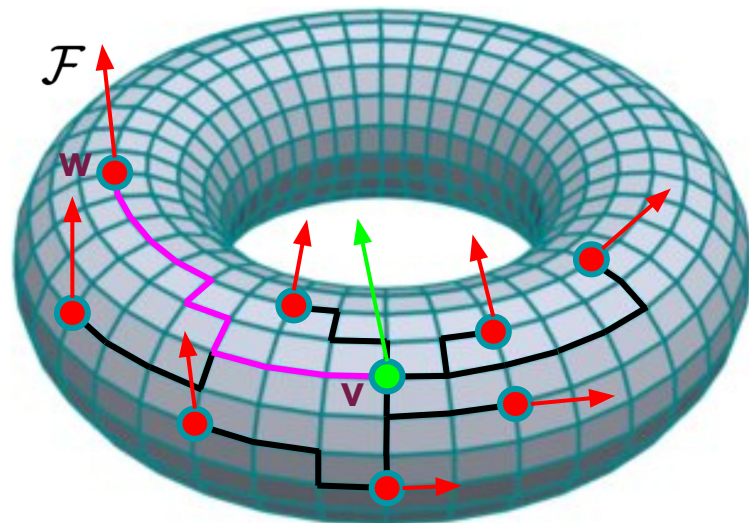
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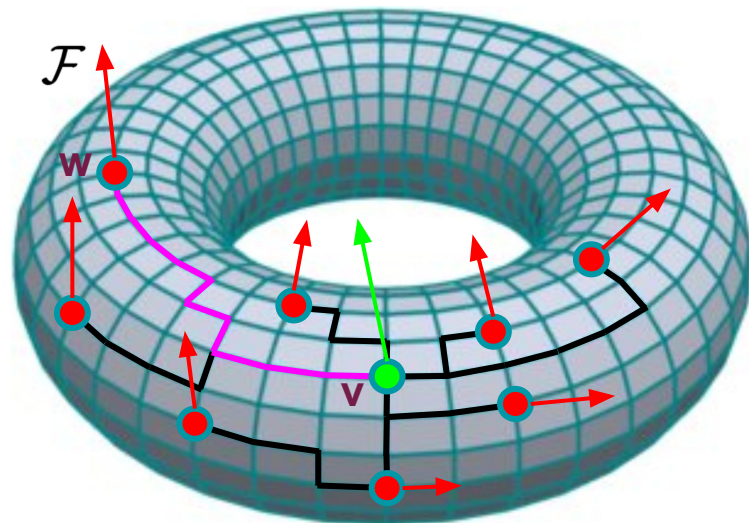
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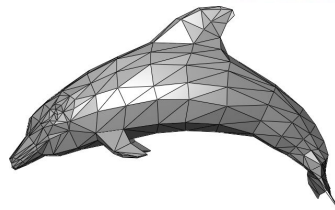
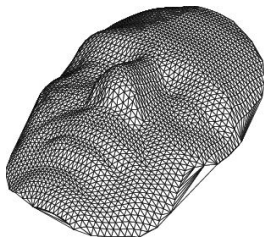
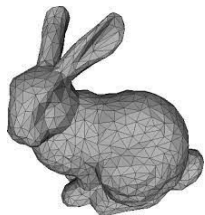
integration over all the nodes

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tensor field defined on the graph



Graph as a discretization of the 2-dim manifold:



Problem formulation: Efficient Graph Field Integration

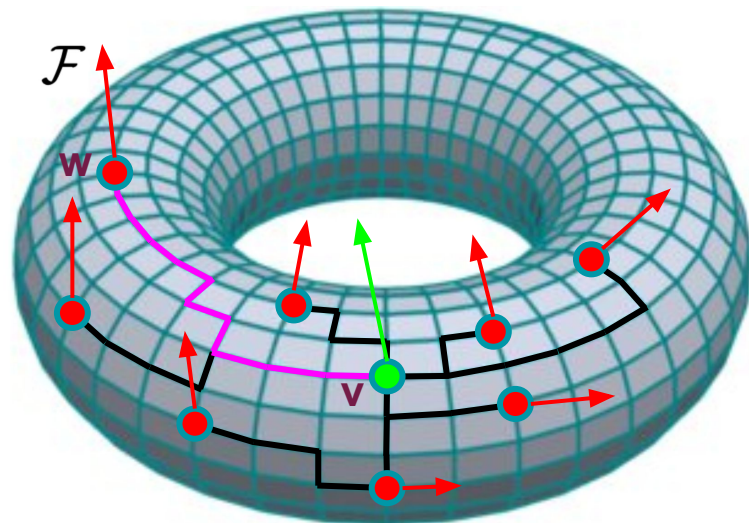
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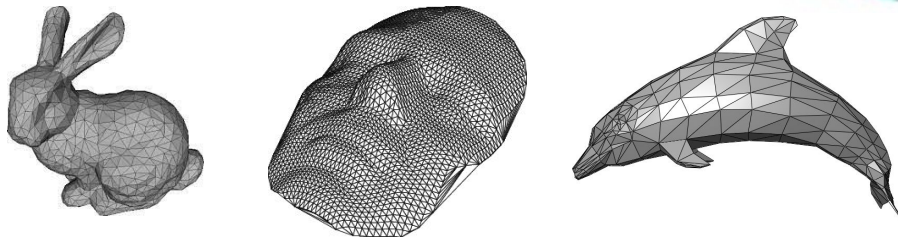
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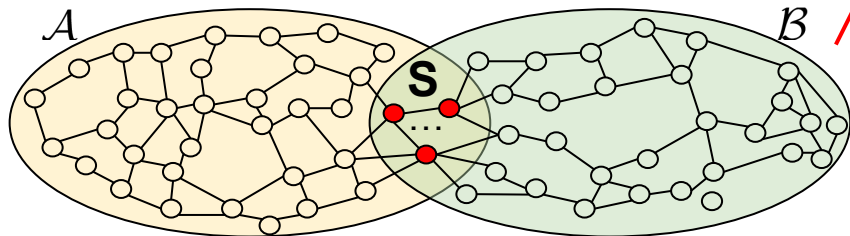
Applications: interpolation on manifolds, topological masking mechanisms for Transformers with structural inputs, physics simulations in curved spaces, Wasserstein barycenter, (Fused) Gromov Wasserstein, ...

Our contributions: SeparatorFactorization (SF) and RFDiffusion (RFD)

SF

- works with input mesh-graphs
- leverages their **low-genus** structure (-> small-size separators)
- applies our new results in structural graph theory on fast graph field integration via separator-based divide-and-conquer methods and Fast Fourier Transform
- $T = O(N \log^2(N))$ time complexity for general K , $T = O(N \log^{1.383\dots}(N))$ if $K := \exp(-\lambda \cdot \text{shortest-path distance})$

most expensive to compute **cross-term contributions** to the integration successfully handled by two signals:



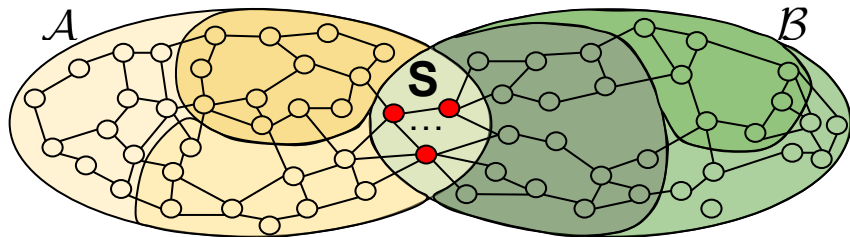
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- residual vectors (the so-called *signature vectors*) giving corrections needed to reach particular nodes of the separator (different-color regions)



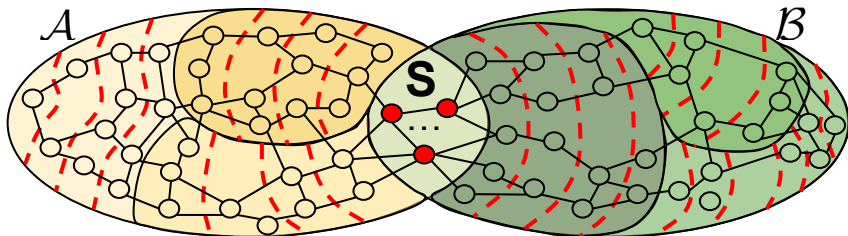
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most expensive to compute **cross-term contributions** to the integration successfully handled by two signals:

- residual vectors (the so-called *signature vectors*) giving corrections needed to reach particular nodes of the separator (different-color regions)
- distance from the separator **S** (red dotted lines)



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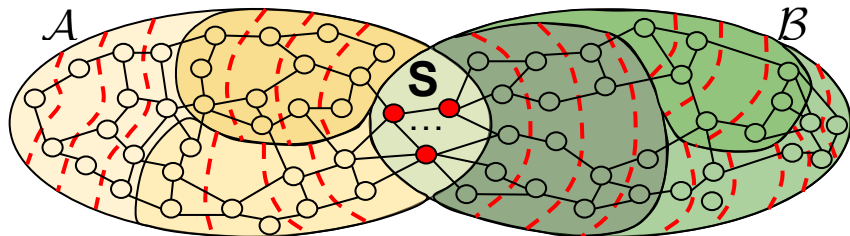
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$$\mathbf{W}_G(i, j) = f(\mathbf{n}_i - \mathbf{n}_j)$$



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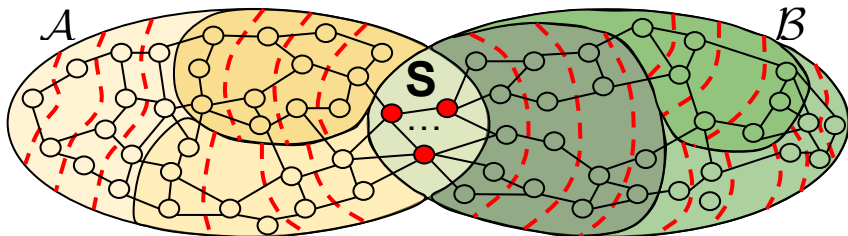
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node representations (e.g. 3d-coords)



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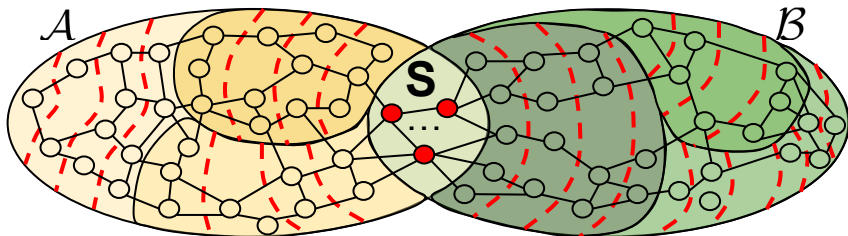
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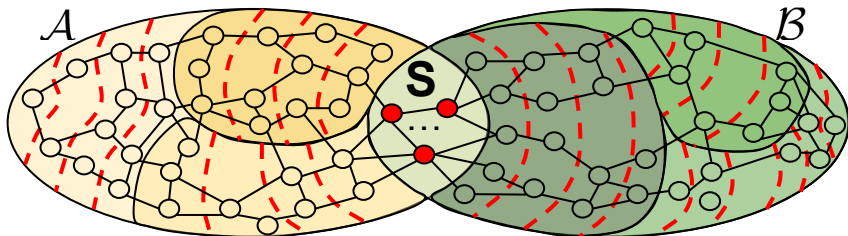
e.g. eps-neighborhood indicator in the particular norm



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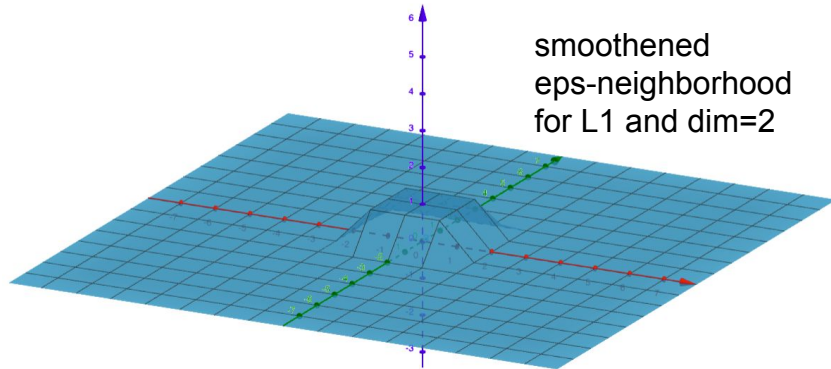


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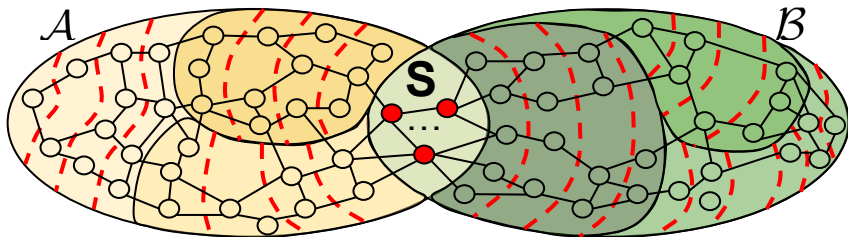
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- linearizes the adjacency matrix via Fourier-Transform based random feature map mechanism:

$$\begin{aligned} f(\mathbf{z}) &= \int_{\mathbb{R}^d} \exp(2\pi i \boldsymbol{\omega}^\top \mathbf{z}) \tau(\boldsymbol{\omega}) d(\boldsymbol{\omega}) \\ &= \int_{\mathbb{R}^d} \exp(2\pi i \boldsymbol{\omega}^\top \mathbf{z}) \frac{\tau(\boldsymbol{\omega})}{p(\boldsymbol{\omega})} p(\boldsymbol{\omega}) d(\boldsymbol{\omega}) \end{aligned}$$



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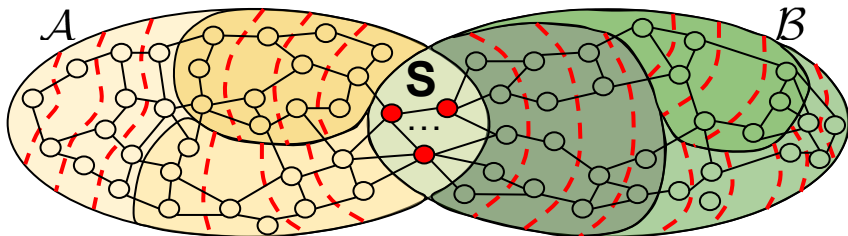
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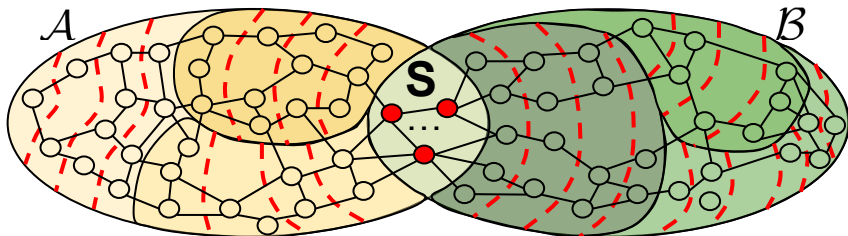
- linearizes the adjacency matrix via Fourier-Transform based random feature map mechanism
- $O(N)$ time complexity, but for a specific class of **graph diffusion kernels**, leveraging our novel decomposition of the exponentials of low-rank matrices:



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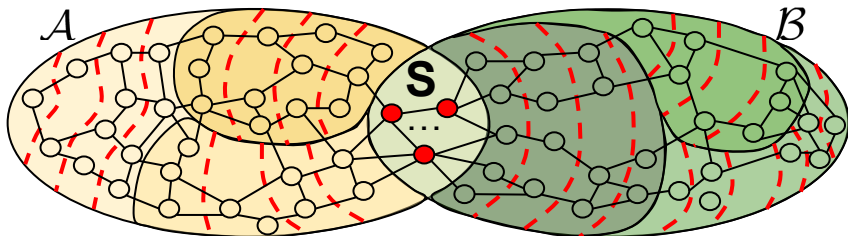
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$$\begin{aligned} \exp(\Lambda \cdot \mathbf{A} \mathbf{B}^\top) &= \sum_{i=0}^{\infty} \frac{1}{i!} (\Lambda \mathbf{A} \mathbf{B}^\top)^i \\ &= \mathbf{I} + \sum_{i=0}^{\infty} \frac{1}{(i+1)!} \mathbf{A} (\Lambda \mathbf{B}^\top \mathbf{A})^{i+1} \mathbf{A}^{-1} \\ &= \mathbf{I} + \mathbf{A} [\exp(\Lambda \mathbf{B}^\top \mathbf{A}) - \mathbf{I}] (\mathbf{B}^\top \mathbf{A})^{-1} \mathbf{B}^\top \end{aligned}$$

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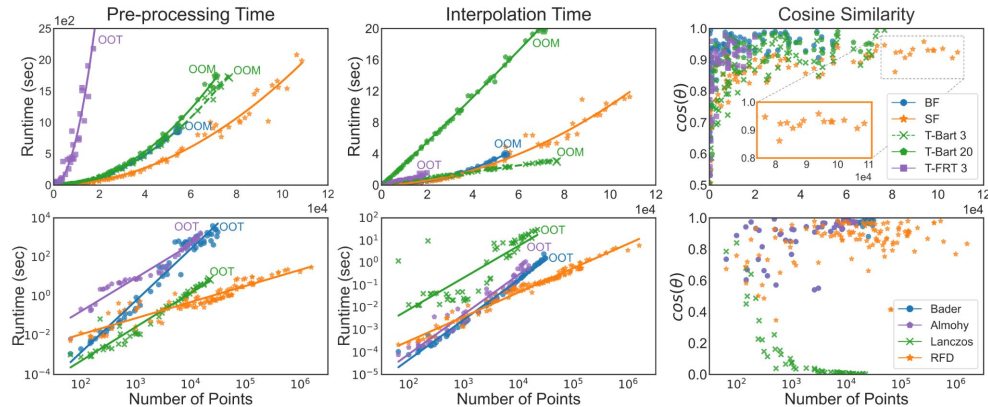
low-rank decomposition of \mathbf{W} via random features

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Experiments

Vertex normal and velocity prediction

- Benchmark on **120** meshes for 3D-printed objects from Thinki10k.
- Compare SF with a naive brute force method (GT) as well as various low distortion tree methods.
- Compare RFD with various algorithms that efficiently compute the action of matrix exponentials.



Wasserstein Distances and Barycenters

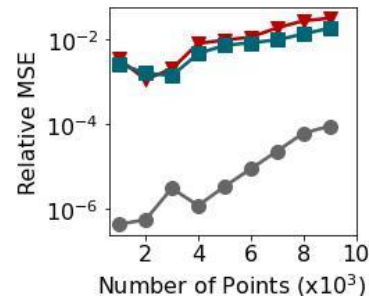
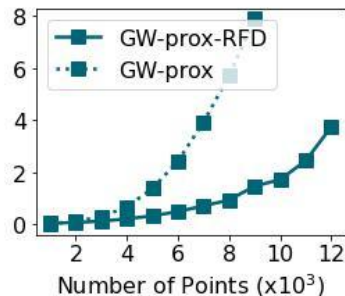
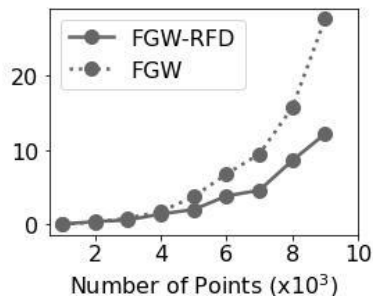
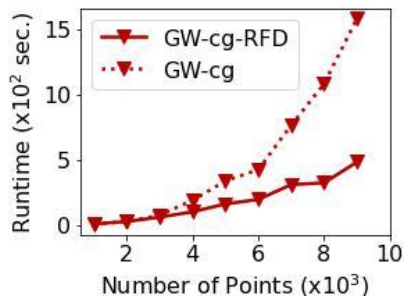
- Integrate our GFI methods into the OT problem of moving masses on a surface mesh, particularly computation of Wasserstein barycenters.
- Geodesic distance on a surface is intractable, so use 2 approximations of this metric:
 - shortest-path distance (SF)
 - distance coming from an ϵ -NN graph approximating the surface (RFD)

Mesh	V	Total Runtime		MSE
		BF	RFD	
Alien	5212	8.06	0.39	0.041
Duck	9862	45.36	1.10	0.002
Land	14738	147.64	2.17	0.017
Octocat	18944	302.84	3.36	0.027

Mesh	V	Total Runtime		MSE
		BF	SF	
Dice	4468	6.8	4.9	0.063
Duck	9862	39.2	19.4	0.002
Land	14738	90.7	38.9	0.015
bubblepot2	18633	113.2	48.3	0.081

(Fused) Gromov Wasserstein distances

- Integrate RFD method in the computation of (Fused) Gromov Wasserstein discrepancy.
- Benchmark it by running extensive speed/accuracy tests on synthetic 3D distributions.



Point Cloud Classification

- Compute the eigendecomposition of the approximated RFD kernel matrix.
- Use 16 smallest eigenvalues for classification on ModelNet10 and Cubes datasets using a random forest.

Dataset	# Graphs	# Classes	Baseline	RFD
ModelNet10	3991/908	10	43.0	70.1
Cubes	3759/659	23	39.3	44.6

- Methods like SPH and LFD on ModelNet achieves about 79%.
- Cubes is challenging and PointNet achieves only 55% accuracy.

Thank You

