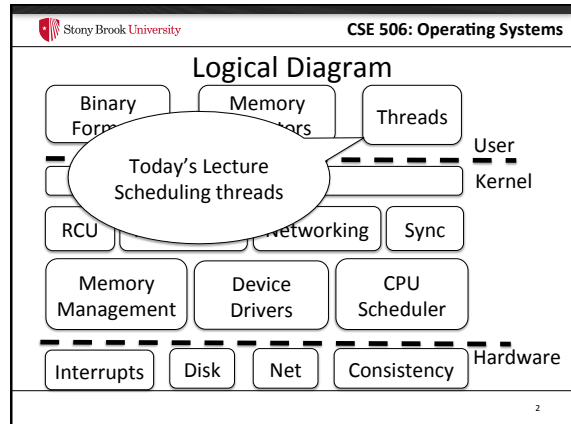


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# Native POSIX Threading Library (NPTL)

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## Today's reading

- Design challenges and trade-offs in a threading library
- Nice practical tricks and system details
- And some historical perspective on Linux evolution

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## Threading review

- What is threading?
  - Multiple threads of execution in one address space
  - x86 hardware:
    - One cr3 register and set of page tables shared by 2+ different register contexts otherwise (rip, rsp/stack, etc.)
  - Linux:
    - One mm\_struct shared by several task\_structs
  - Does JOS support threading?

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## Ok, but what is a thread library?

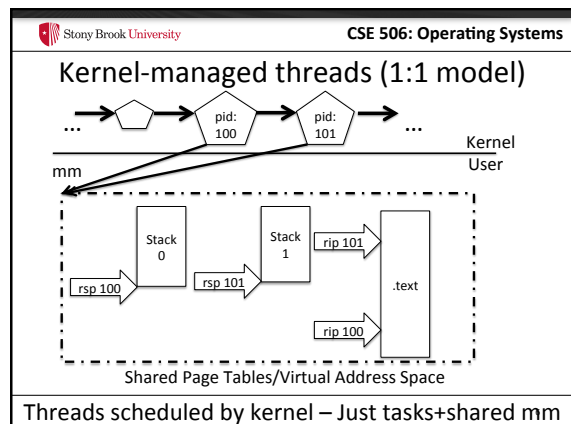
- Threading APIs provided by libpthread.so

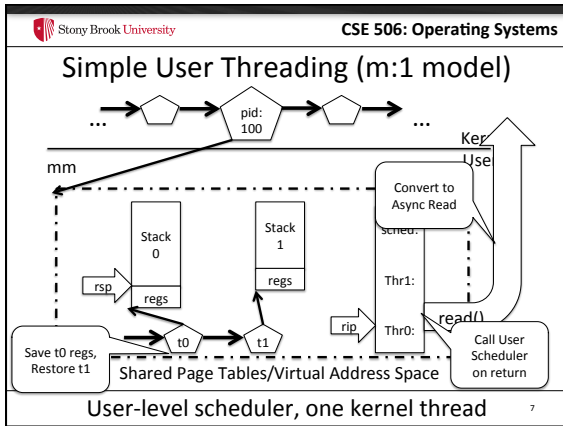
libpthread.so	Linux System Call
pthread_create()	clone(CLONE_FS CLONE_IO CLONE_THREAD ...)
pthread_mutex_lock(), pthread_cond_wait(),...	futex()
Thread-local storage	arch_prctl()

- System calls tend to be subtle, hard to program
  - Design reflects performance concerns

The division of labor is part of the design!

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- ### User Threading Observations
- One can easily switch stacks in user-space
    - No privileged instructions needed
    - Same for saving and restoring PC (rip)
  - Convert blocking to non-blocking calls
    - OS must provide non-blocking equivalents
    - Transparent help from libc
      - Catch futexes, yield
      - Add O\_ASYNC to open, detect when data ready
  - Need a second, user-level thread scheduler

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- ### Generalization – m:n model
- Multiple application-level threads (m)
  - Multiplexed on n kernel-visible threads (m >= n)
    - N often number of CPUs

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- ### User Threading Complexity
- Lots of libc/libpthread changes
    - Working around “unfriendly” kernel API
  - Bookkeeping gets much more complicated
    - Second scheduler
    - Synchronization different
  - Can do crude preemption using:
    - Certain functions (locks)
    - Timer signals from OS
    - Signals

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- ### Why bother with user threading?
- Context switching overheads
  - Finer-grained scheduling control
  - Blocking I/O

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- ### Context Switching Overheads
- Recall: Forking a thread halves your time slice
    - Takes a few hundred cycles to get in/out of kernel
      - Plus cost of switching a thread
    - Time in the scheduler counts against your timeslice
  - 2 threads, 1 CPU
    - If I can run the context switching code locally (avoiding trap overheads, etc), my threads get to run slightly longer!
    - Stack switching code works in userspace with few changes

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### Finer-Grained Scheduling Control

- Example: Thread 1 has a lock, Thread 2 waiting for lock
  - Thread 1's quantum expired
  - Thread 2 just spinning until its quantum expires
  - Wouldn't it be nice to donate Thread 2's quantum to Thread 1?
    - Both threads will make faster progress!
- Similar problems with producer/consumer, barriers, etc.
- Deeper problem: Application's data flow and synchronization patterns hard for kernel to infer

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### Blocking I/O

- I have 2 threads, they each get half of the application's quantum
  - If A blocks on I/O and B is using the CPU
  - B gets half the CPU time
  - A's quantum is "lost" (at least in some schedulers)
- Modern Linux scheduler:
  - A gets a priority boost
  - Maybe application cares more about B's CPU time...

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### Blocking I/O and Events

- Events: abstraction for dealing with blocking I/O
- Layered over a user-level scheduler
- Lots of literature on this topic if you are interested...

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### Scheduler Activations

- Better API for user-level threading
  - Not available on Linux
  - Some BSDs support(ed) scheduler activations
- On any blocking operation, kernel *upcalls* back to user scheduler
- Eliminates most libc changes
  - Easier notification of blocking events
- User scheduler keeps kernel notified of how many runnable tasks it has (via system call)
  - Kernel allocates up to that many scheduler activations

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### What is a scheduler activation?

- Like a kernel thread:
  - A kernel stack and a user-mode stack
  - Represents the allocation of a CPU time slice
- Not like a kernel thread:
  - Does not automatically resume a user thread
  - Goes to one of a few well-defined "upcalls"
    - New timeslice, Timeslice expired, Blocked SA, Unblocked SA
    - Upcalls must be reentrant (called on many CPUs at same time)
  - User scheduler decides what to run

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### Downsides of scheduler activations

- A random user thread gets preempted on every scheduling-related event
  - Not free!
  - User scheduling must do better than kernel by a big enough margin to offset these overheads
- Moreover, the most important thread may be the one to get preempted, slowing down critical path
  - Potential optimization: communicate to kernel a preference for which activation gets preempted to notify of an event

### Optional Reading on Scheduler Activations

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## Back to NPTL

- Ultimately, a 1:1 model was adopted by Linux.
- Why?
  - Higher context switching overhead (lots of register copying and upcalls)
  - Difference of opinion between research and kernel communities about how inefficient kernel-level schedulers are. (claims about  $O(1)$  scheduling)
  - Way more complicated to maintain the code for m:n model. Much to be said for encapsulating kernel from thread library!

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## Meta-observation

- Much of 90s OS research focused on giving programmers more control over performance
  - E.g., microkernels, extensible OSes, etc.
- Argument: clumsy heuristics or awkward abstractions are keeping me from getting full performance of my hardware
- Some won the day, some didn't
  - High-performance databases generally get direct control over disk(s) rather than go through the file system

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## User-threading in practice

- Has come in and out of vogue
  - Correlated with how efficiently the OS creates and context switches threads
- Linux 2.4 – Threading was really slow
  - User-level thread packages were hot
- Linux 2.6 – Substantial effort went into tuning threads
  - E.g., Most JVMs abandoned user-threads

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## Other issues to cover

- Signaling
  - Correctness
  - Performance (Synchronization)
- Manager thread
- List of all threads
- Other miscellaneous optimizations

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## What was all the fuss about signals?

- 2 issues:
  - 1) The behavior of sending a signal to a multi-threaded process was not correct. And could never be implemented correctly with kernel-level tools (pre 2.6)
    - Correctness: Cannot implement POSIX standard
  - 2) Signals were also used to implement blocking synchronization. E.g., releasing a mutex meant sending a signal to the next blocked task to wake it up.
    - Performance: Ridiculously complicated and inefficient

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## Issue 1: Signal correctness w/ threads

- Mostly solved by kernel assigning same PID to each thread
  - 2.4 assigned different PID to each thread
  - Different TID to distinguish them
- Problem with different PID?
  - POSIX says I should be able to send a signal to a multi-threaded program and any unmasked thread will get the signal, *even if the first thread has exited*
- To deliver a signal kernel has to search each task in the process for an unmasked thread

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## Issue 2: Performance

- Solved by adoption of futexes
- Essentially just a shared wait queue in the kernel
- Idea:
  - Use an atomic instruction in user space to implement fast path for a lock (more in later lectures)
  - If task needs to block, ask the kernel to put you on a given futex wait queue
  - Task that releases the lock wakes up next task on the futex wait queue
- See optional reading on futexes for more details

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## Manager Thread

- A lot of coordination (using signals) had to go through a manager thread
  - E.g., cleaning up stacks of dead threads
  - Scalability bottleneck
- Mostly eliminated with tweaks to kernel that facilitate decentralization:
  - The kernel handled several termination edge cases for threads
  - Kernel would write to a given memory location to allow lazy cleanup of per-thread data

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## List of all threads

- A pain to maintain
- Mostly eliminated, but still needed to eliminate some leaks in fork
- Generation counter is a useful trick for lazy deletion
  - Used in many systems
  - Idea: Transparently replace key “Foo” with “Foo:0”. Upon deletion, require next creation to rename “Foo” to “Foo:1”. Eliminates accidental use of stale data.

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## Other misc. optimizations

- On super-computers, were hitting the 8k limit on segment descriptors
- Where does the 8k limit come from?
  - Bits in the segment descriptor. Hardware-level limit
- How solved?
  - Essentially, kernel scheduler swaps them out if needed
  - Is this the common case?
  - No, expect 8k to be enough

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## Optimizations

- Optimized exit performance for 100k threads from 15 minutes to 2 seconds!
- PID space increased to 2 billion threads
  - /proc file system able to handle more than 64k processes


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## Results

- Big speedups! Yay!

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<h3>Summary</h3>	
<ul style="list-style-type: none"><li>• Nice paper on the practical concerns and trade-offs in building a threading library<ul style="list-style-type: none"><li>– I enjoyed this reading very much</li></ul></li><li>• Understand 1:1 vs. m:n model<ul style="list-style-type: none"><li>– User vs. kernel-level threading</li></ul></li><li>• Understand other key implementation issues discussed in the paper</li></ul>	
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